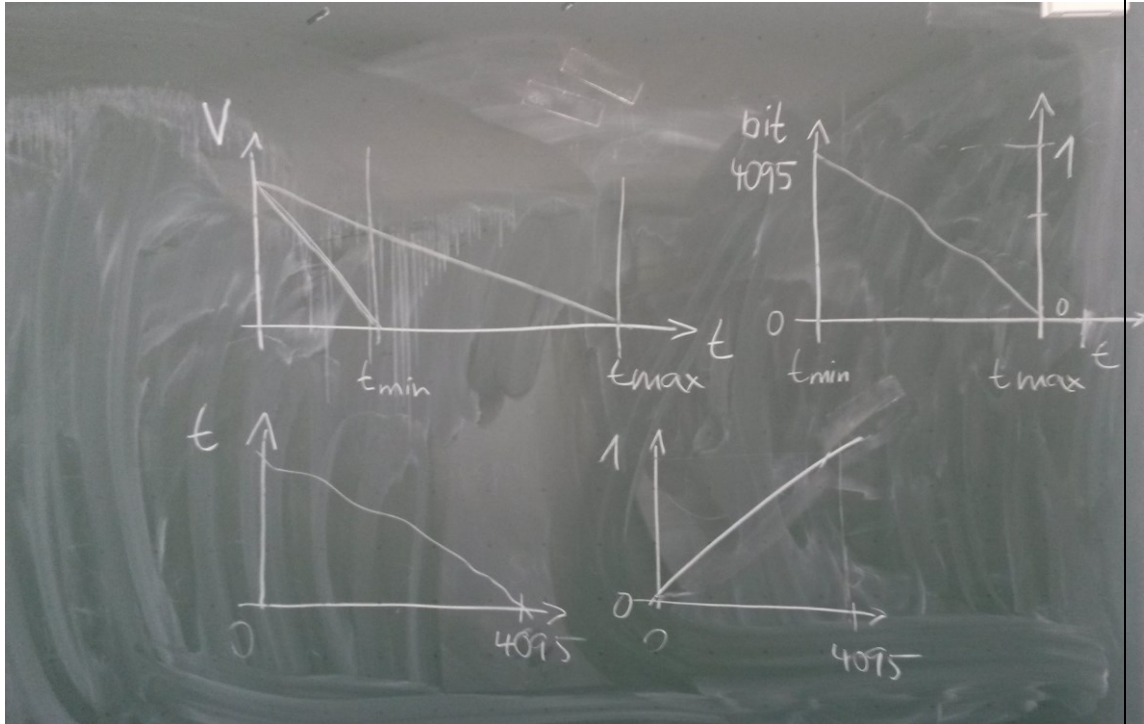


<b>Meeting:</b> Coordination meeting on Bumper time calibration			
<b>Date:</b>	2016-03-08 10:30-11:30	<b>Chair:</b> WG	<b>Minutes:</b> WG
<b>Participants:</b>	Kraus, Ingrid; Krause, Udo; Mueller, Raphael; Pfeil, Regine		
<b>Distribution:</b>	Participants + stakeholders	<b>Doc-ID:</b>	F-EP-YR-BumperTimeCalib
A: Action, D: Decision, I: Information			Who o Due Date
<b>1. Background</b>			
<p>The Crying injection bumper (YR01LBx) is an electrostatic device consisting of 4 pairs of electrodes and is required to perform multi-turn injection with ion beam from the local injector. The required high-voltage applied to the electrodes is provided by a custom-made power supply which can be switched manually between two operation modes / voltage ranges. Behind the scenes these two voltage ranges are realized by switching between two physical power supplies.</p> <p>The high voltage delivered as output of the supply has a specific time structure (the voltage falls linearly from a maximum value to zero within an adjustable time, see <a href="#">documentation document in Sharepoint</a>) which can be controlled by sending a 12Bit set value to the supply providing a set value range from 0-4095. One specialty of this control is, that the maximum value 4095 sets the minimum time and 0 the maximum and that the response of the supply to the set value is not linear – i.e. doubling the set value does not double the fall time. Hence, the set-value to fall-time behavior has to be measured /calibrated by SBDE and has to be considered in an appropriate way in the control system.</p>			
<b>2. Where shall the calibration data be stored?</b>			
<p>Two possible places of storing the calibration data were discussed:</p> <ul style="list-style-type: none"> <li>• Hard-code the time structure in a FESA class</li> <li>• Store calibration curve in LSA-DB/CDB</li> </ul> <p>Decision: The data shall be stored in the LSA-DB as polynomial calibration curves.</p> <p>Assumptions &amp; open points:</p> <ul style="list-style-type: none"> <li>• A: The set-value to fall-time response can be modeled as polynomial</li> <li>• A: CDB will be the entry point for the data which will be provided by SBDE</li> <li>• OP: What will be the proper Device Class in CDB to attach this data to? Power Converters? Post meeting note: WG checked in CDB which Devices Classes he can use → only “NC Magnets” were available in the selector (user dependency?)</li> <li>• OP: Are the required unit types (seconds/set value) already available in CDB?</li> </ul>			
<b>3. How shall the set value be represented in the interface of the FESA class?</b>			
<p>Three possible options were discussed:</p> <ol style="list-style-type: none"> <li>1. The set-value shall be represented without conversion as 0-4095 integer</li> <li>2. The set-value shall be represented by a 0-1 decimal value, where 0 is the maximum time, 1 is</li> </ol>			

- the minimum time
3. The set-value shall be represented by a 0-1 decimal value, where 0 is the minimum time, 1 is the maximum time



Decision:

- The set-value shall be represented by option 2 to provide a certain level of user-friendliness and device-agnostic interface.
- SBDE shall provide calibration data based on the normalized (0-1) scale

#### 4. How shall the conversion be handled?

Questions came up if the set-value scale conversion will be done linearly (1:1) or might require non-linear conversion?

Decision:

- The scale shall be normalized linearly ( $S_{\text{normalized}}(\text{set-value}) = 1/4095 * \text{set-value}$ )

#### 5. Representation of the power supply/ies in FESA

Questions aroused if the Bumper power supply shall be represented in FESA as 1 device (approach in last meeting on the Bumper power) or rather as 2 devices. The second approach has some advantages with respect to detecting incompatible system settings concerning physical switch at the device and choice of power supply in the software.

Decision:

- The decision of last meeting was confirmed. The Bumper power supply shall be represented as 1 device in FESA. Possible inconsistent states during operation will be caught by interlock and shall be prevented by administration/training.